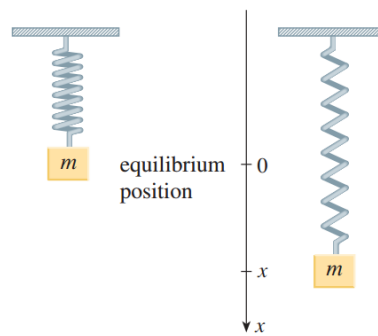


Ordinary Differential Equation (ODE): Initial-Value Problems

Objectives

- Knowing how to implement the Euler's and Runge-Kutta (RK) methods for the first-order and the second-order ODEs.

Most of physical problems are described through the differential equations. For example, we can describe the movement of a spring-mass system from Hook's Law:



$$F = kx \quad (1)$$

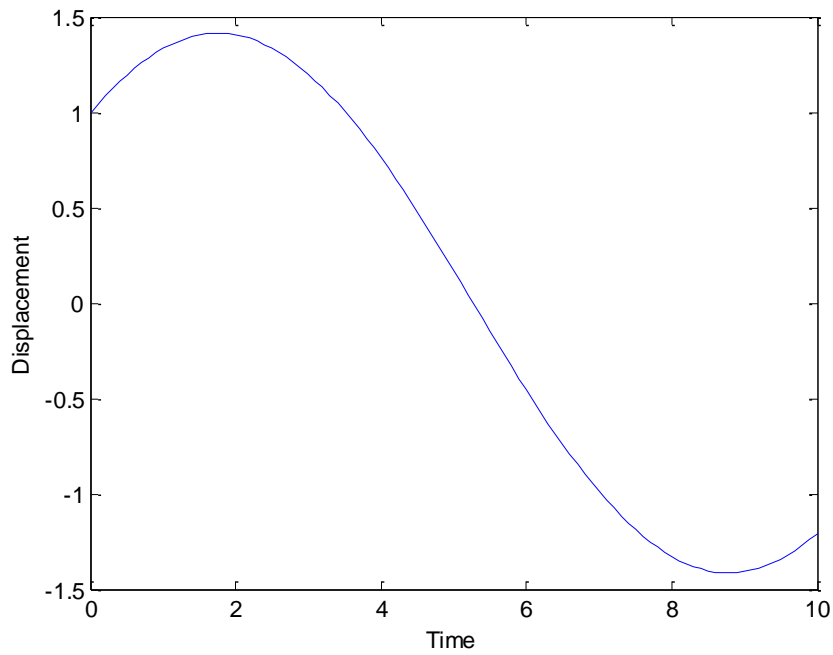
Where F = force, k = a spring constant, and x = the displacement of spring. From Newton's Second Law, we have

$$m \frac{d^2x}{dt^2} + kx = 0 \quad (2)$$

Using an analytical method, the general solution of Eq. (2) is

$$x(t) = c_1 \cos \sqrt{\frac{k}{m}}t + c_2 \sin \sqrt{\frac{k}{m}}t \quad (3)$$

The example of the spring movement obtained from Eq. (3) is shown in the following figure.



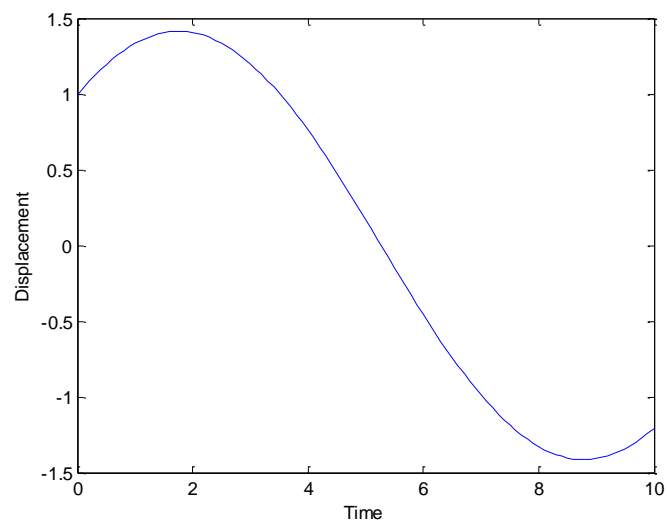
Euler's Method

This section is devoted to solving the first-order ordinary differential equations of the form

$$\frac{dy}{dt} = f(t, y) \quad (4)$$

With initial condition $y(t_0) = y_0$.

This method estimates y_{i+1} from y_i by performing the linear extrapolation as follows:



The slope of the estimated line is

$$\text{slope} = \frac{dy}{dt} = \frac{y_{i+1} - y_i}{t_{i+1} - t_i} = f(t_i, y_i) \quad (5)$$

To estimate y_{i+1} from Eq. (5), we have

$$y_{i+1} = y_i + f(t_i, y_i)(t_{i+1} - t_i) \quad (6)$$

Let $t_{i+1} - t_i = h$ which is a step size for estimation.

Thus, Eq. (6) can be written as

$$y_{i+1} = y_i + f(t_i, y_i)h \quad (7)$$

The estimation in Eq. (7) can be expressed in the general form of approximation as

$$y_{i+1} = y_i + \phi h \quad (8)$$

Where ϕ is an incremental function.

According to the similarity between the approximation using Euler's Method and the general form of approximation, the incremental function, ϕ , for Euler's Method is

$$\phi = f(t_i, y_i) \quad (9)$$

Runge-Kutta (RK) Method

From the the general form of approximation,

$$y_{i+1} = y_i + \phi h \quad (8)$$

For Runge-Kutta (RK) Method, the incremental function can be written in general form as

$$\phi = a_1 k_1 + a_2 k_2 + \dots + a_n k_n \quad (9)$$

Where the a's are constant and the k's are

$$k_1 = f(t_i, y_i) \quad (9a)$$

$$k_2 = f(t_i + p_1 h, \quad y_i + q_{11} k_1 h) \quad (9b)$$

$$k_3 = f(t_i + p_2 h, \quad y_i + q_{21} k_1 h + q_{22} k_2 h) \quad (9c)$$
$$\vdots$$

$$k_n = f(t_i + p_{n-1} h, \quad y_i + q_{n-1,1} k_1 h + q_{n-1,2} k_2 h + \dots + q_{n-1,n-1} k_{n-1} h) \quad (9d)$$

Where the p's and q's are constants.

The most popular RK method are fourth order. **The general form for the fourth-order RK method** is given by

$$y_{i+1} = y_i + \frac{1}{6}(k_1 + 2k_2 + 2k_3 + k_4)h \quad (10)$$

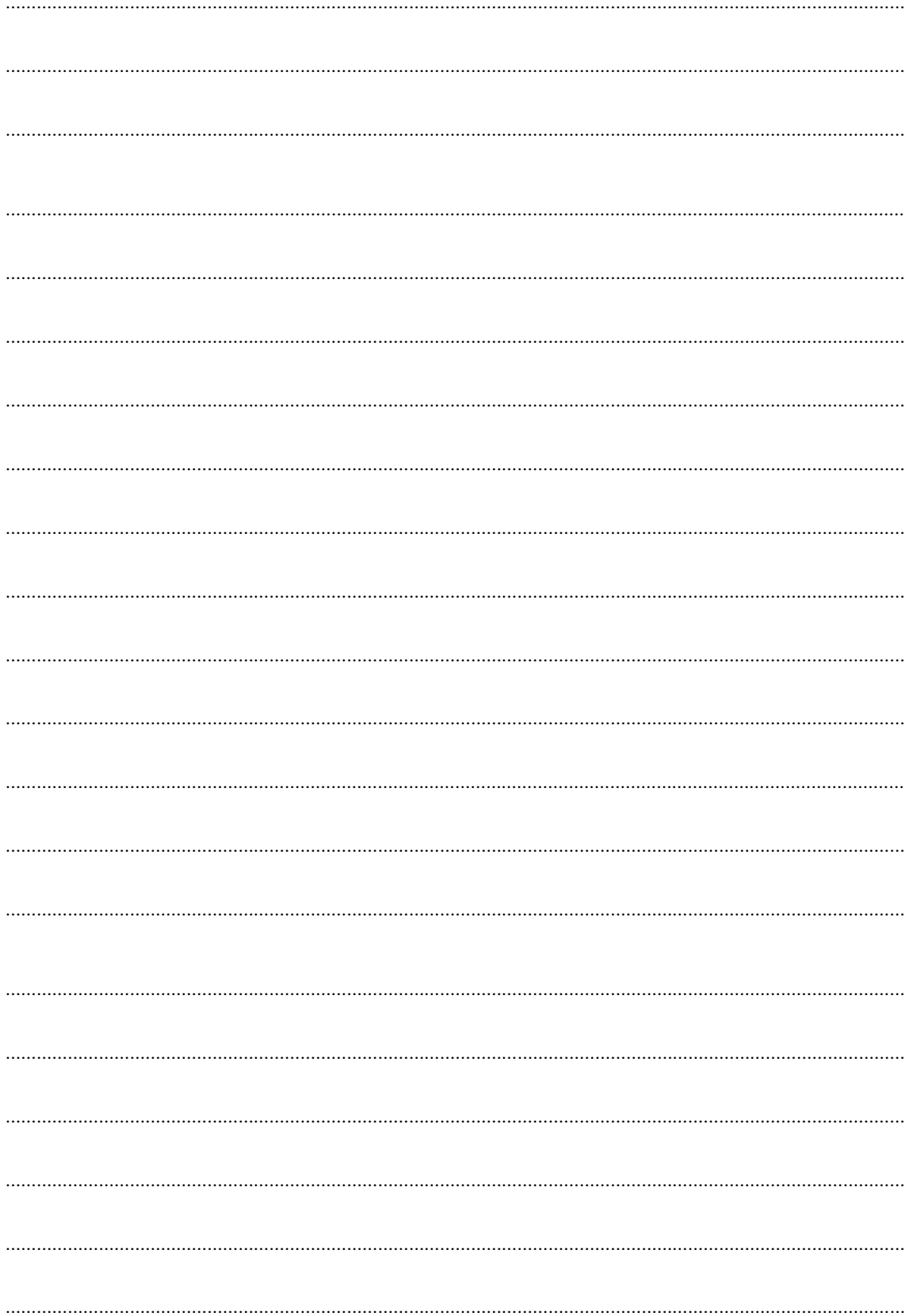
Where

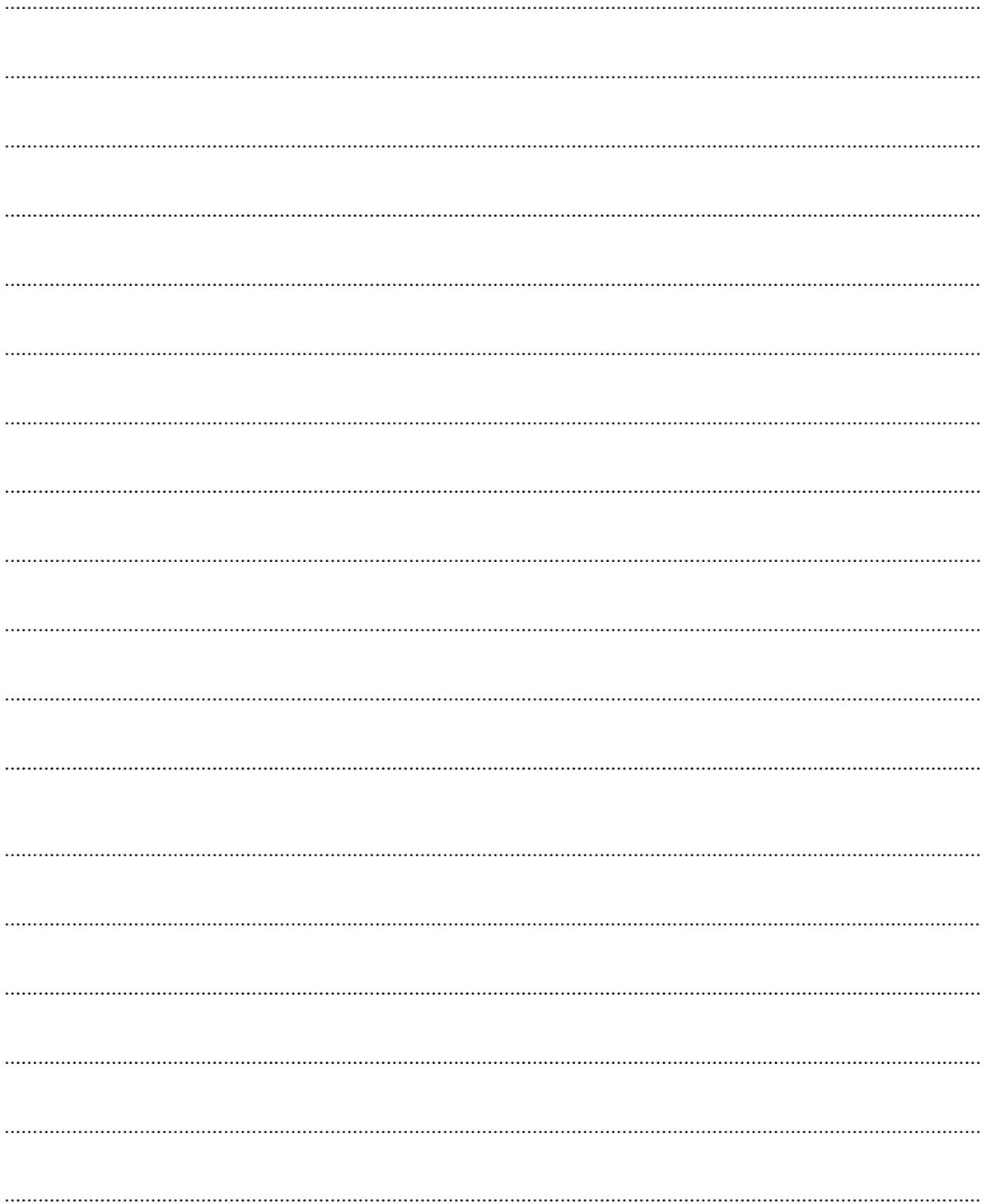
$$k_1 = f(t_i, y_i) \quad (11)$$

$$k_2 = f\left(t_i + \frac{1}{2}h, \quad y_i + \frac{1}{2}k_1 h\right) \quad (12)$$

$$k_3 = f\left(t_i + \frac{1}{2}h, \quad y_i + \frac{1}{2}k_2 h\right) \quad (13)$$

$$k_4 = f(t_i + h, \quad y_i + k_3 h) \quad (14)$$





Exercise

1. Solve the following initial value problem over the interval from $t=0$ to 2.

$$\frac{dy}{dt} = yt^3 - 1.5y$$

- a) Using analytical method.
b) Using Euler's method with $h = 0.5$ and 0.25 .
c) Using the fourth-order RK method with $h = 0.5$.
2. The van der Pol equation is a model of an electronic circuit that arose back in the days of vacuum tubes:

$$\frac{d^2y}{dt^2} - (1 - y^2)\frac{dy}{dt} + y = 0$$

Given the initial conditions, $y(0) = y'(0) = 1$, solve this equation from $t = 0$ to 10 using Euler's method with a step size of **(a)** 0.2 and **(b)** 0.1.

3. Solve the following pair of ODEs over the interval from $t = 0$ to 0.4 using a step size of 0.1. The initial conditions are $y(0) = 2$ and $z(0) = 4$. Obtain your solution with (a) Euler's method and (b) the fourth-order RK method.

$$\frac{dy}{dt} = -2y + 5ze^{-1}$$

$$\frac{dz}{dt} = -\frac{yz^2}{2}$$